

2.2

$$4(a) \quad z_1 = r_1 (\cos \theta + i \sin \theta); \quad \bar{z}_1 = r_1 (\cos \theta - i \sin \theta)$$

$$= r_1 [\cos(-\theta) + i \sin(-\theta)]$$

$$\begin{array}{c|c} S & A \\ \hline T & C \end{array}$$

$$\begin{cases} \cos \theta = \cos(-\theta) \\ \sin(-\theta) = -\sin \theta \end{cases}$$

$$z_2 = r_2 (\cos \alpha + i \sin \alpha); \quad \bar{z}_2 = r_2 (\cos \alpha - i \sin \alpha)$$

$$= r_2 [\cos(-\alpha) + i \sin(-\alpha)]$$

$$z_1 z_2 = r_1 r_2 [\cos(\theta + \alpha) + i \sin(\theta + \alpha)] \quad \text{using the properties of modulus and argument}$$

$$|z_1 z_2| = |z_1| |z_2| \quad \text{and} \quad \arg(z_1 z_2) = \arg z_1 + \arg z_2$$

similarly

$$\therefore \overline{z_1 z_2} = r_1 r_2 [\cos(-\theta - \alpha) + i \sin(-\theta - \alpha)]$$

$$\bar{z}_1 \times \bar{z}_2 = r_1 [\cos(-\theta) + i \sin(-\theta)] r_2 [\cos(-\alpha) + i \sin(-\alpha)]$$

$$= r_1 r_2 [\cos(-\theta) \cos(-\alpha) + i (\cos(-\theta) \sin(-\alpha) + \sin(-\theta) \cos(-\alpha) - \sin(-\theta) \sin(-\alpha))]$$

$$= r_1 r_2 [\cos(-\theta - \alpha) + i \sin(-\theta - \alpha)]$$

$$= \overline{z_1 z_2}$$

2.2

$$4(b) \quad z = r(\cos\theta + i\sin\theta); \quad \bar{z} = r(\cos\theta - i\sin\theta)$$

$$\frac{1}{z} = \frac{1}{r(\cos\theta + i\sin\theta)}$$

Multiply numerator and denominator by  $\cos\theta - i\sin\theta$

$$\therefore \frac{1}{z} = \frac{1}{r(\cos\theta + i\sin\theta)} \times \frac{\cos\theta - i\sin\theta}{\cos\theta - i\sin\theta}$$

$$= \frac{\cos\theta - i\sin\theta}{r(\cos^2\theta + \sin^2\theta)}$$

$$= \frac{1}{r} \times (\cos\theta - i\sin\theta)$$

$$\therefore \left(\frac{1}{z}\right) = \frac{1}{r}(\cos\theta + i\sin\theta)$$

Now consider  $\frac{1}{\bar{z}}$

$$\frac{1}{\bar{z}} = \frac{1}{r(\cos\theta - i\sin\theta)}$$

Multiply numerator and denominator by  $\cos\theta + i\sin\theta$

$$\therefore \frac{1}{\bar{z}} = \frac{1}{r(\cos\theta - i\sin\theta)} \times \frac{\cos\theta + i\sin\theta}{\cos\theta + i\sin\theta}$$

$$= \frac{\cos\theta + i\sin\theta}{r(\cos^2\theta + \sin^2\theta)}$$

$$= \frac{1}{r}(\cos\theta + i\sin\theta)$$

$$= \left(\frac{1}{z}\right) \text{ as required.}$$

2.2 let  $z_1 = r_1(\cos\theta + i\sin\theta)$ ;  $z_2 = r_2(\cos\alpha + i\sin\alpha)$

4 (c)  $\left| \frac{z_1}{z_2} \right| = \frac{|z_1|}{|z_2|}$  This is a known property

$\arg\left(\frac{z_1}{z_2}\right) = \arg z_1 - \arg z_2$  This is a known property

$\therefore \frac{z_1}{z_2} = \frac{r_1}{r_2} [\cos(\theta - \alpha) + i\sin(\theta - \alpha)]$

$\therefore \overline{\left(\frac{z_1}{z_2}\right)} = \frac{r_1}{r_2} [\cos(\theta - \alpha) - i\sin(\theta - \alpha)]$   
 $= \frac{r_1}{r_2} [\cos(-(\theta - \alpha)) + i\sin(-(\theta - \alpha))]$

Now let's look at  $\bar{z}_1$  and  $\bar{z}_2$ .

$\bar{z}_1 = r_1(\cos\theta - i\sin\theta)$ ;  $\bar{z}_2 = r_2(\cos\alpha - i\sin\alpha)$

$\bar{z}_1 = r_1[\cos(-\theta) + i\sin(-\theta)]$ ;  $\bar{z}_2 = r_2[\cos(-\alpha) + i\sin(-\alpha)]$

Note:  $\frac{S}{T} \mid \frac{A}{C} \Rightarrow \begin{matrix} \cos(-\theta) = \cos\theta \\ \sin(-\theta) = -\sin\theta \end{matrix}$

$\left| \frac{\bar{z}_1}{\bar{z}_2} \right| = \frac{|\bar{z}_1|}{|\bar{z}_2|}$  This is a known property

$= \frac{r_1}{r_2}$

$\arg\left(\frac{\bar{z}_1}{\bar{z}_2}\right) = \arg(\bar{z}_1) - \arg(\bar{z}_2) = -\theta - (-\alpha) = \alpha - \theta$

$\therefore \frac{\bar{z}_1}{\bar{z}_2} = \frac{r_1}{r_2} [\cos(\alpha - \theta) + i\sin(\alpha - \theta)]$

$$\begin{aligned}
 4(c) \text{ But } \overline{\left(\frac{z_1}{z_2}\right)} &= \frac{r_1}{r_2} \left[ \cos(-( \theta - \alpha )) + i \sin(-( \theta - \alpha )) \right] \\
 &= \frac{r_1}{r_2} \left[ \cos(\alpha - \theta) + i \sin(\alpha - \theta) \right] \\
 &= \frac{\overline{z_1}}{\overline{z_2}} \text{ as required.}
 \end{aligned}$$


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5. You won't be able to do this until you have studied Extension 1 Mathematical Induction.